

Stochastic Differential Equations, Part II

Evelyn Buckwar

Department of Mathematics
Heriot-Watt University, Edinburgh
e.buckwar@hw.ac.uk
<http://www.ma.hw.ac.uk/~eb51>



Overview

- ▷ Stochastic differential equations
- ▷ Some methods
- ▷ Strong convergence
- ▷ Stability issues
- ▷ Remarks on weak methods

SODEs

Consider Itô stochastic ordinary differential equations (SODEs) on $[0, T]$

$$X(s) \Big|_0^t = \int_0^t f(s, X(s)) \, ds + \sum_{r=1}^m \int_0^t g_r(s, X(s)) \, dB_r(s), \quad X(0) = X_0$$

with $f : [0, T] \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ and $G = (g_1, \dots, g_m) : [0, T] \times \mathbb{R}^n \rightarrow \mathbb{R}^{n \times m}$. B is an m -dim. Brownian motion on a suitable probability space, X_0 is a given initial value, independent of the Brownian motion and with finite second moment, i.e. $\mathbb{E}|X_0|^2 < \infty$.

Numerics for Stochastic Ordinary Differential Equations

Integral equation on $t \in [0, T]$:

$$X(t) = x_0 + \int_0^t f(s, X(s))ds + \int_0^t G(s, X(s))dB(s)$$

Define:

Grid on $[0, T]$, step-size $h := T/N$ and $t_n = n \cdot h$, $n = 0, \dots, N$,
 $I^{t_n, t_{n+1}} = \int_{t_n}^{t_{n+1}} dB(s) = B(t_{n+1}) - B(t_n) \sim \sqrt{h}\mathcal{N}(0, 1)$.

Simplest numerical method: **Euler-Maruyama-method**

$$X_{n+1} = X_n + h f(t_n, X_n) + G(t_n, X_n) I^{t_n, t_{n+1}}$$

Numerical methods

A basic numerical method: Θ -Maruyama scheme

grid on $[0, T]$ with step-size $h := T/N$ and $t_n = n \cdot h$, $n = 1, \dots, N - 1$

$$\begin{aligned} X_n &= X_{n-1} + h(\Theta f(t_n, X_n) + (1 - \Theta) f(t_{n-1}, X_{n-1})) \\ &\quad + \sum_{r=1}^m g_r(t_{n-1}, X_{n-1}) I_r^{t_{n-1}, t_n} \end{aligned}$$

where

$$I_r^{t_{n-1}, t_n} = B_r(t_n) - B_r(t_{n-1}) \sim \mathcal{N}(0, h)$$

$\Theta = 0$: Euler-Maruyama method

The Milstein method

$$\begin{aligned} X_n &= X_{n-1} + h f(t_{n-1}, X_{n-1}) + \sum_{r=1}^m g_r(t_{n-1}, X_{n-1}) I_r^{t_{n-1}, t_n}, \\ &+ \sum_{r_1, r_2=1}^m (g_{r_1})'_x g_{r_2}(t_{n-1}, X(t_{n-1})) I_{r_1, r_2}^{t_{n-1}, t_n} \end{aligned}$$

where again

$$I_r^{t_{n-1}, t_n} = B_r(t_n) - B_r(t_{n-1}) \sim \mathcal{N}(0, h)$$

and also

$$I_{r_1, r_2}^{t_{n-1}, t_n} = \int_{t_{n-1}}^{t_n} \int_{t_{n-1}}^s dB_{r_1}(u) dB_{r_2}(s)$$

Generation of paths of Brownian motion

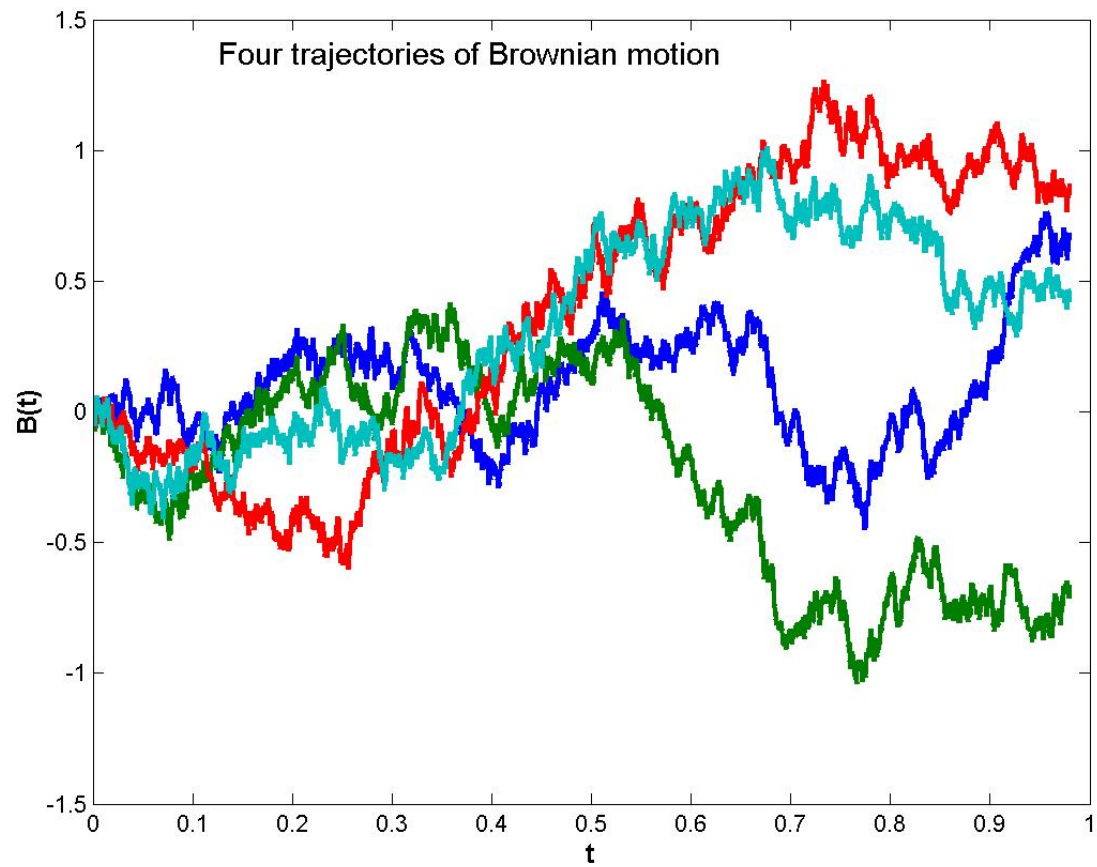
$$\text{Construction: } B(t_n) = B(0) + \sum_{i=0}^{n-1} (B(t_{i+1}) - B(t_i))$$

where $B(t) - B(s)$ is a $\sqrt{t-s}\mathcal{N}(0, 1)$ distr. random variable, $0 \leq s < t \leq T$,

$\mathcal{N}(0, 1)$ either comes from e.g., matlab, R, etc or can be calculated from uniform r.v. over $(0, 1)$ (probably currently best: Mersenne twistor)

Polar-Marsaglia:

```
generate(double *g1, double *g2) {  
    double v1,v2,w,lw;  
  
    do  
        { v1 = 2.0 * frand()-1.0;  
          v2 = 2.0 * frand()-1.0;  
          w  = v1 * v1 + v2 * v2;  
        }  
    while (!(w<=1.0) && (w>0.0)); /* obviously ln(0) does not exist  
    lw = log(w)/w;  
    lw = sqrt(-lw-lw);  
    *g1 = v1*lw;  
    *g2 = v2*lw;  
}
```

Questions:

How do we understand the quality of the approximations?

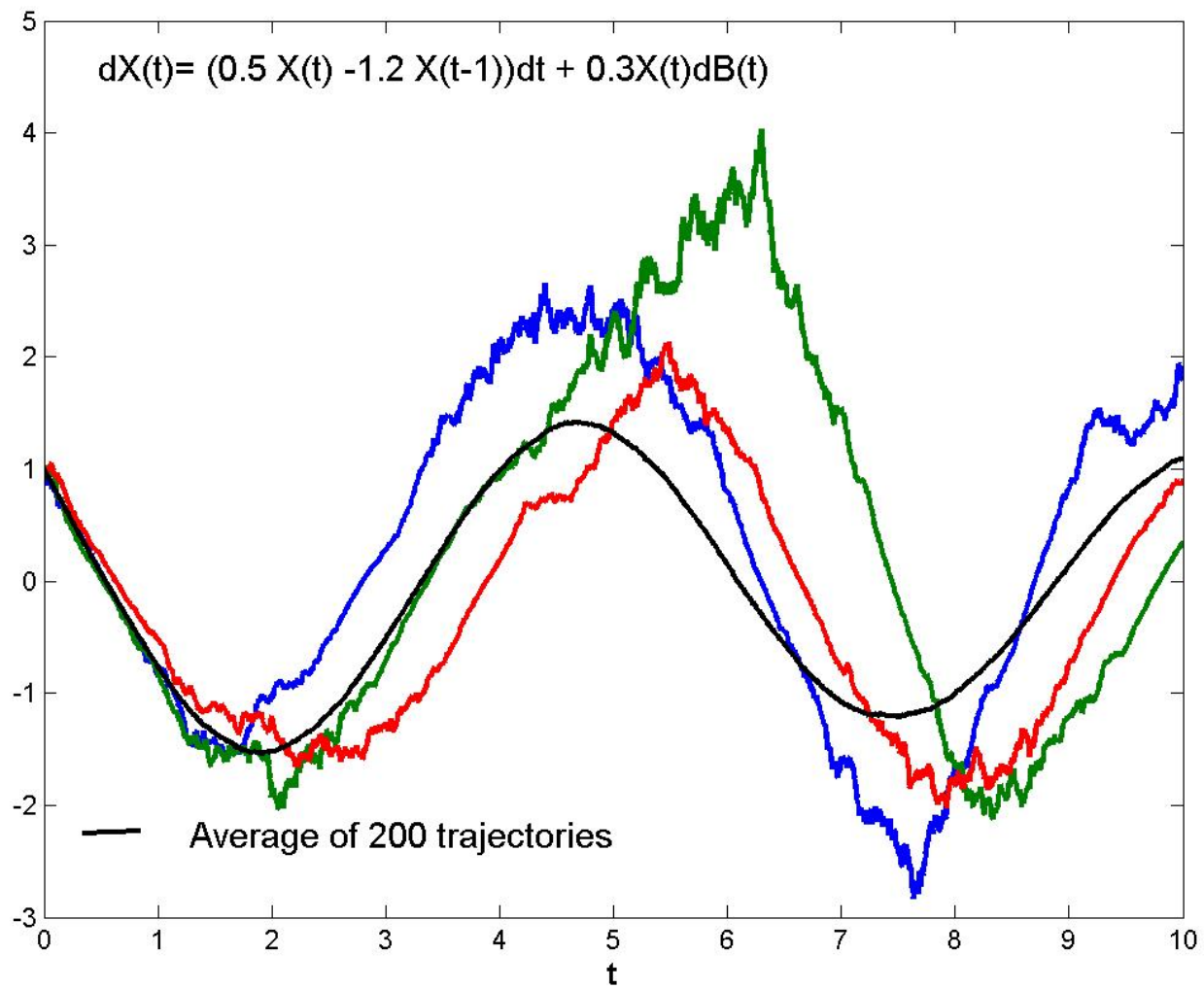
How do we analyse the quality?

How do we construct methods?

Two Modes of Convergence

- ▶ Strong convergence measures the (mean-square) difference of *paths* of the analytical and numerical solution; simulations used for visualisation of dynamics, filtering.

- ▶ Weak approximations are concerned with calculating the expectation of some functional of the solution $\mathbb{E} \Psi(X(t_n))$ where Ψ could be the moments of the process, concerned with distributional properties of the processes, [Monte-Carlo-methods](#),



One-step methods

Let Y_n denote the numerical approximation of the exact solution $X(t_n)$ of an Itô SODE at time t_n on the given grid, where Y_n is given by a stochastic explicit one-step scheme of the form

$$Y_{n+1} = Y_n + \Phi(Y_n, h_n, t_n, I^{t_n, t_n+h_n}), \quad n = 0, \dots, N-1$$

with initial value $Y_0 = X_0$. We call the function Φ the increment function of the method. The term $I^{t, t+h}$ denotes a collection of multiple stochastic integrals over the subinterval $[t, t+h]$

$$I_{r_1, r_2, \dots, r_j}^{t, t+h} = \int_t^{t+h} \int_t^{s_1} \dots \int_t^{s_{j-1}} dB_{r_1}(s_j) \dots dB_{r_j}(s_1),$$

where $r_i \in \{0, 1, \dots, m\}$ and $dB_0(s) = ds$.

Strong Convergence

We call a numerical method **mean-square convergent** if the global error $X(t_n) - X_n$ satisfies

$$\max_{n=1,\dots,N} \|X(t_n) - Y_n\|_{L_2} \rightarrow 0 \text{ as } h \rightarrow 0,$$

we say the method is **mean-square convergent with order γ** ($\gamma > 0$) if the global error satisfies

$$\max_{n=1,\dots,N} \|X(t_n) - Y_n\|_{L_2} \leq C \cdot h^\gamma \text{ as } h \rightarrow 0$$

($C > 0$ indep. of h).

Norm $\|Z\|_{L_2} := (\mathbb{E}|Z|^2)^{1/2}$.

Define mean-square consistency via the local error

$$L_n = X(t_{n+1}) - X(t_n) - \Phi(X(t_n), h_n, t_n, I^{t_n, t_n+h}), \quad n = 0, \dots, N-1$$

of the method, measured in the mean ($\|\mathbb{E}(L_n | \mathcal{F}_{t_n})\|_{L_2}$) and in the mean-square ($\|L_n\|_{L_2}$).

Consistency measures the amount by which the numerical method fails to produce the true solution over one (small) interval $[t_n, t_n + h]$. The measurement in the mean ensures that the deterministic part of the SODE is approximated appropriately.

One can show that under Lipschitz conditions in the mean and the mean-square on the increment function Φ , that is

$$\text{(Lip1)} \quad \left| \mathbb{E}(\Phi(u_1, h, t, I^{t,t+h}) - \Phi(u_2, h, t, I^{t,t+h}) | \mathcal{F}_t) \right| \leq Lh|u_1 - u_2|,$$

$$\text{(Lip2)} \quad \mathbb{E}\left(\left| \Phi(u_1, h, t, I^{t,t+h}) - \Phi(u_2, h, t, I^{t,t+h}) \right|^2 | \mathcal{F}_t \right) \leq L^2 h |u_1 - u_2|^2.$$

mean-square consistency of order γ implies mean-square convergence of the same order. Thus, we need to check two Lipschitz conditions and estimate the local error, using the Itô formula and a 'counting lemma'

Lemma (Milstein, Tretyakov): For any function ϕ sufficiently smooth, and any t on the grid, and step-size $h > 0$, such that $t+h$ is also on the grid, we have that

$$\begin{aligned} \mathbb{E}(I_{r_1 \dots r_j}^{t, t+h}(\phi) | \mathcal{F}_t) &= 0 \quad \text{if } r_i \neq 0 \quad \text{for some } i \in \{1, \dots, j\}, \\ \|\mathbb{E}(I_{r_1, \dots, r_j}^{t, t+h}(\phi) | \mathcal{F}_t)\|_{L_2} &\leq \|I_{r_1, \dots, r_j}^{t, t+h}(\phi)\|_{L_2} = \mathcal{O}(h^{l_1+l_2/2}), \end{aligned}$$

where l_1 is the number of zero indices r_i , and l_2 the number of nonzero indices r_i .

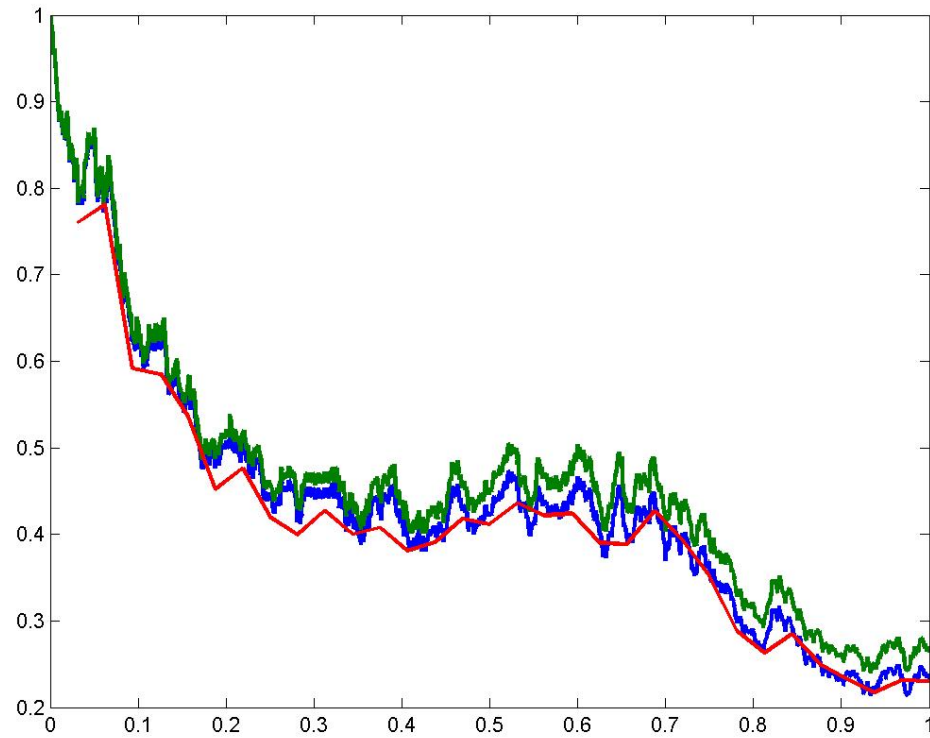
What happens for Stratonovich equations?

If we apply the Euler-Maruyama method

$$X_{n+1} = X_n + h f(t_n, X_n) + G(t_n, X_n) I^{t_n, t_{n+1}}$$

to

$$dX(t) = f(t, X(t)) dt + g(t, X(t)) \circ dB(t)$$

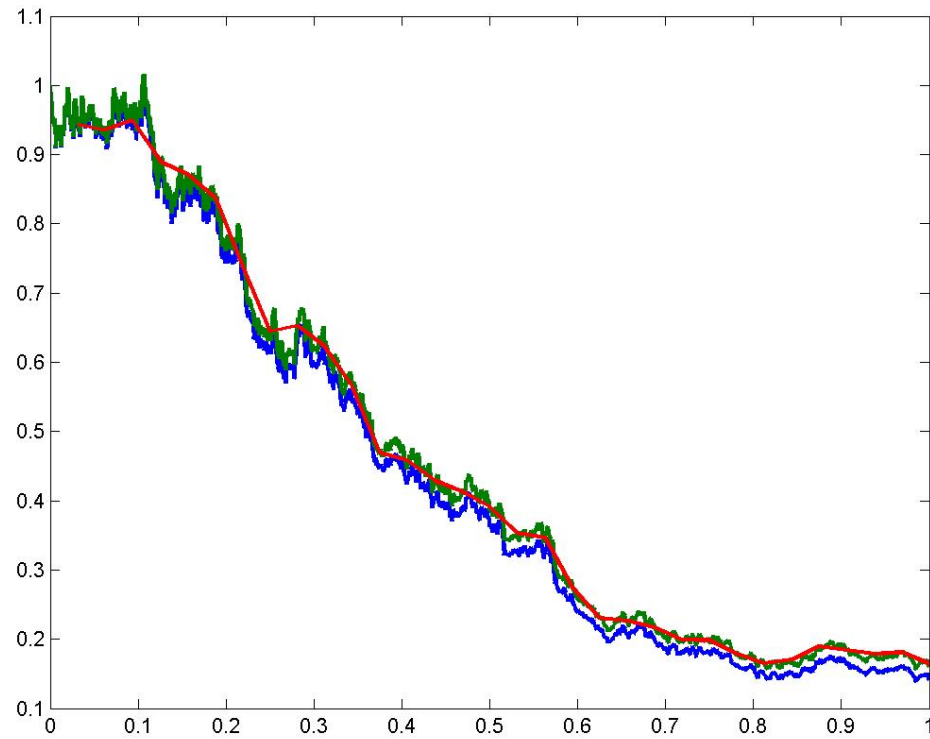


Need to be consistent with Stratonovich calculus!

Try Heun-method

$$X_{n+1} = X_n + h f(t_n, X_n) + \frac{1}{2}(G(t_n, X_n) + G(t_n, \tilde{X}_n)) I^{t_n, t_{n+1}}$$

where $\tilde{X}_{n+1} = X_n + h f(t_n, X_n) + G(t_n, X_n) I^{t_n, t_{n+1}}$



are there other methods?

SODEs with **small noise**

Itô stochastic ordinary differential equations (SODEs) on $\mathcal{J} := [0, T]$

$$X(s) \Big|_0^t = \int_0^t f(s, X(s)) \, ds + \epsilon \int_0^t G(s, X(s)) \, dW(s), \quad X(0) = X_0$$

with $f : \mathcal{J} \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ and $G = (g_1, \dots, g_m) : \mathcal{J} \times \mathbb{R}^n \rightarrow \mathbb{R}^{n \times m}$.
 W is an m -dim. Wiener process on $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \in \mathcal{J}}, \mathbb{P})$, X_0 is a given \mathcal{F}_0 -measurable initial value, independent of the Wiener process and with finite second moment. $\epsilon \ll 1!$

We assume that there exists a path-wise unique strong solution $X(\cdot)$ of the above equation.

Stochastic linear two-step Maruyama method (SL2MM)

for $n = 2, 3, \dots$ with given i.v. $X_0, X_1 \in L_2(\Omega, \mathbb{R}^n)$

$$\sum_{j=0}^2 \alpha_{2-j} X_{n-j} = h \sum_{j=0}^2 \beta_{2-j} f(t_{n-j}, X_{n-j}) + \sum_{j=1}^2 \gamma_j \sum_{r=1}^m g(t_{n-j}, X_{n-j}) I_r^{t_{n-j}, t_{n-j+1}}$$

mean-square convergence theory in [B., Winkler, SINUM, 2006](#)

$\alpha_2 = 1$, $\gamma_1 = \alpha_2 = 1$ and $\gamma_2 = \alpha_2 + \alpha_1$

E.g.: BDF2-Maruyama method: $\alpha_2 = 1$, $\alpha_1 = -\frac{4}{3}$, $\alpha_0 = \frac{1}{3}$, $\beta_2 = \frac{2}{3}$,
 $\beta_1 = \beta_0 = 0$, $\gamma_1 = 1$ and $\gamma_2 = -\frac{1}{3}$

Numerical results

$$X(t) = 1 + \int_0^t \alpha X(s) ds + \int_0^t \beta X(s) dW(s), \quad t \in [0, 1], \quad (\text{scalar})$$

with solution (gBm) $X(t) = \exp\left(\left(\alpha - \frac{1}{2}\beta^2\right)t + \beta W(t)\right)$

maximum approximate L_2 -norm of the global errors on $[0, 1]$:

$$\max_{\ell=1, \dots, N} \left(\frac{1}{M} \sum_{j=1}^M |X(t_\ell, \omega_j) - X_\ell(\omega_j)|^2 \right)^{1/2} \approx \max_{\ell=1, \dots, N} \|X(t_\ell) - X_\ell\|_{L_2}$$

$N \equiv$ number of steps, $M \equiv$ number of computed paths ($M = 100$)

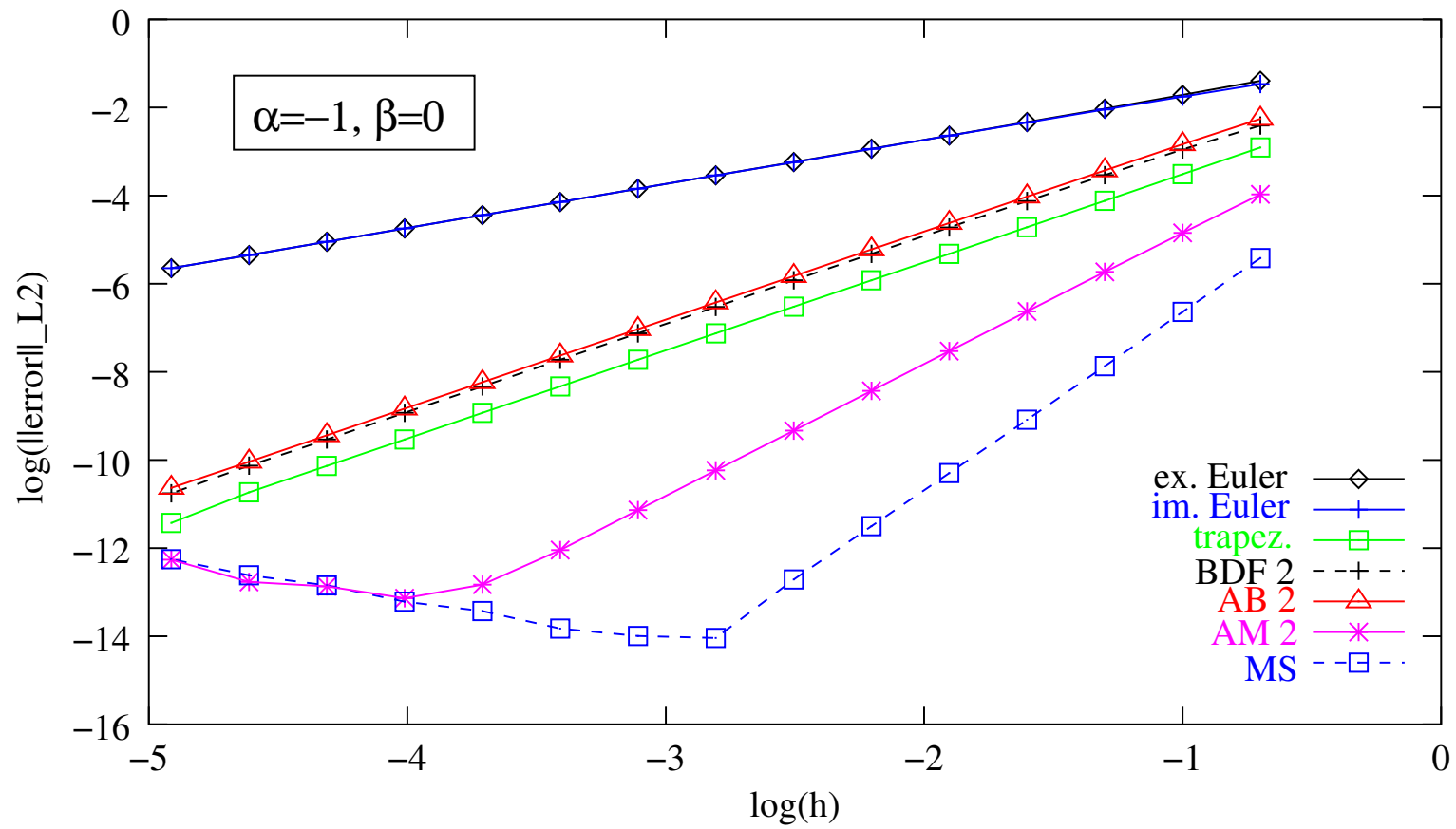


Figure 2

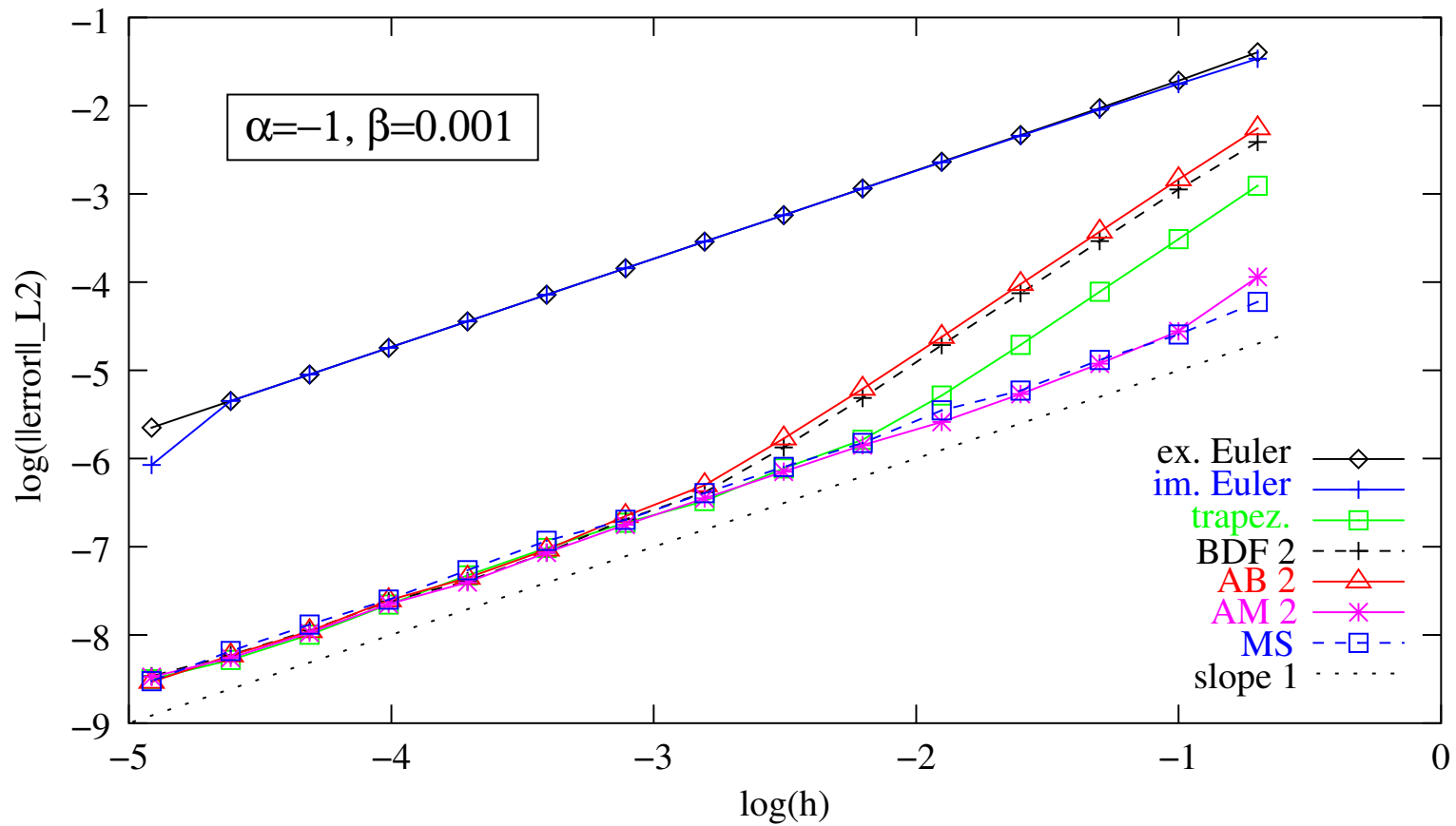


Figure 3

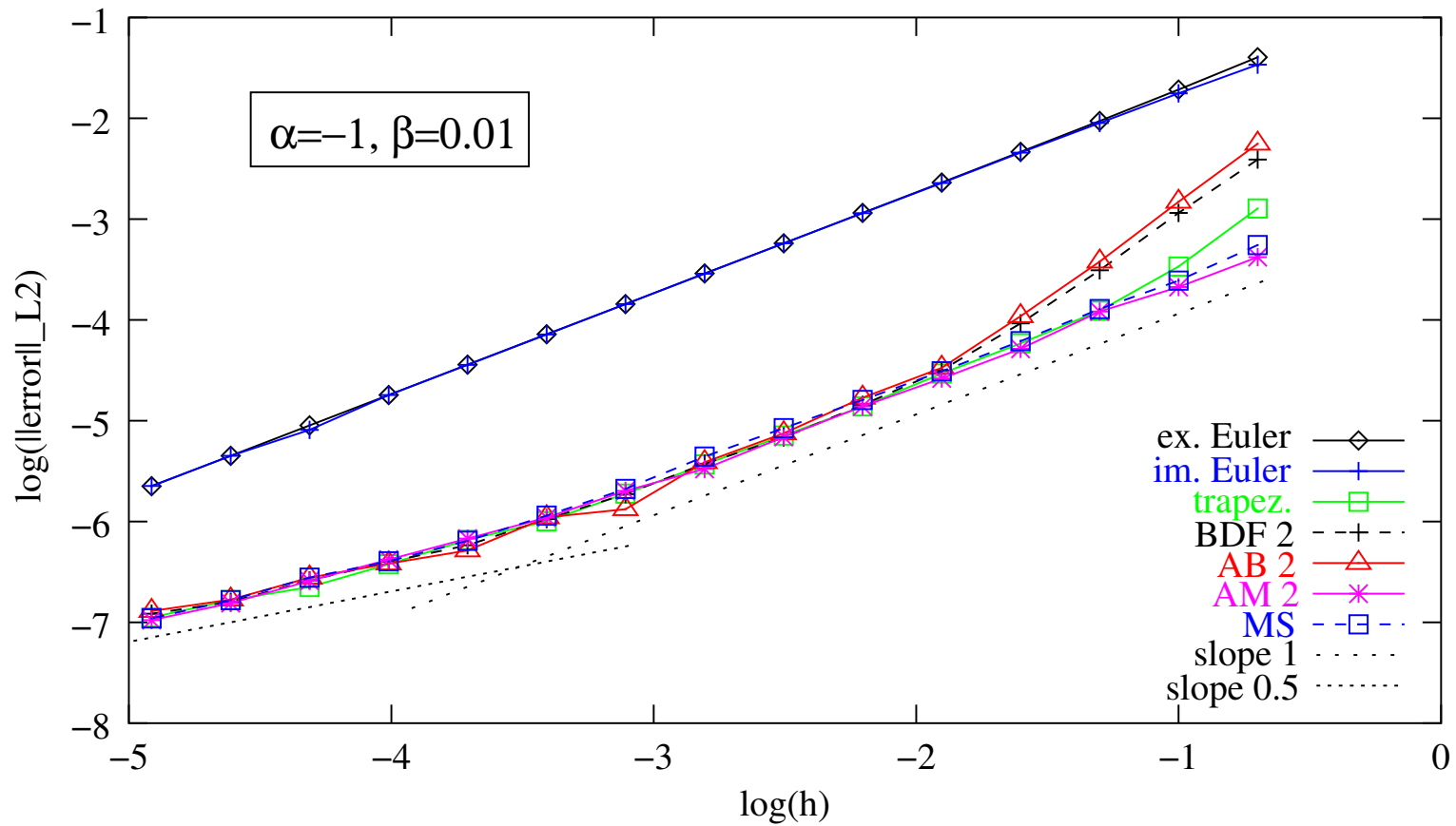


Figure 4

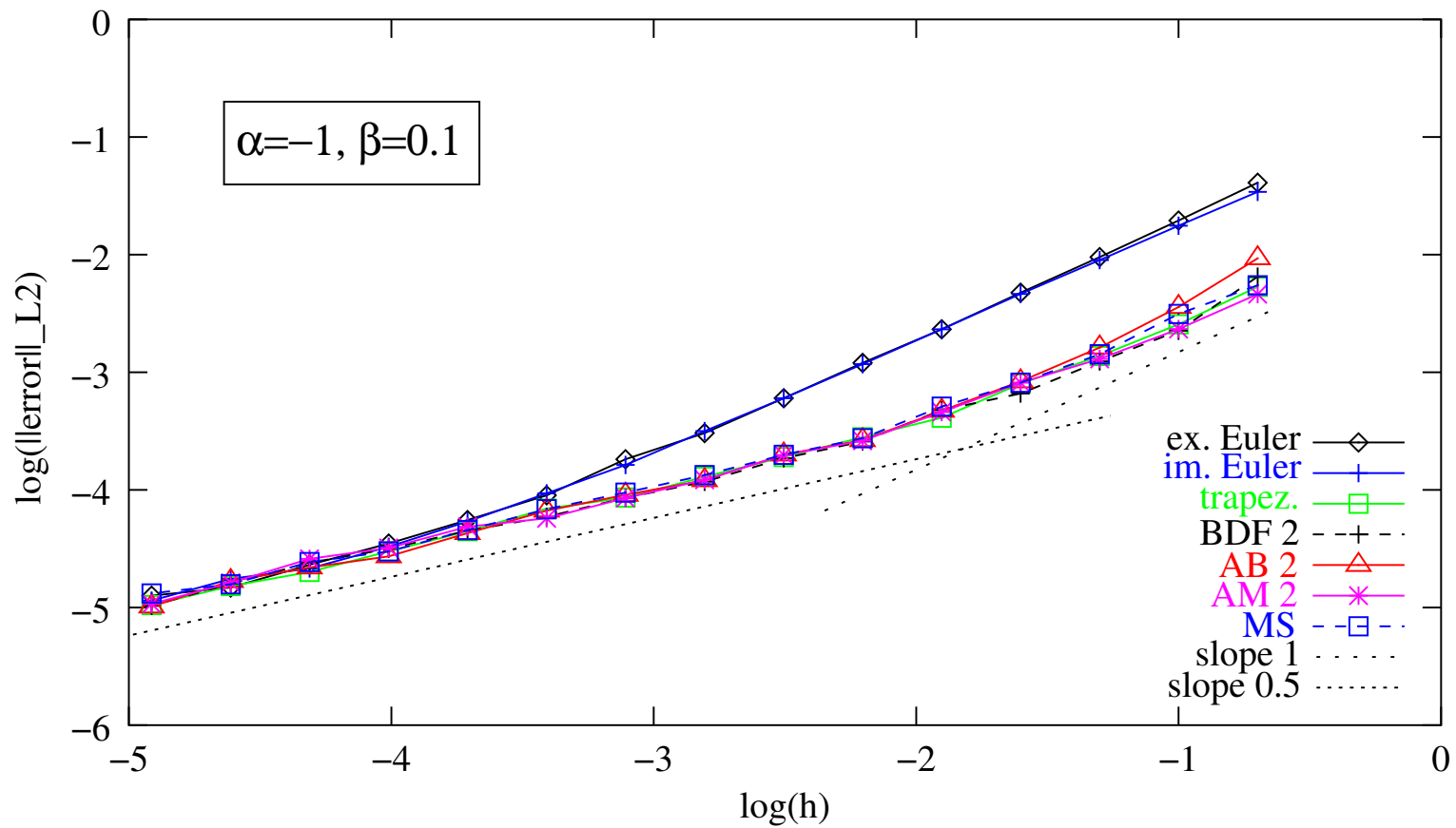


Figure 5

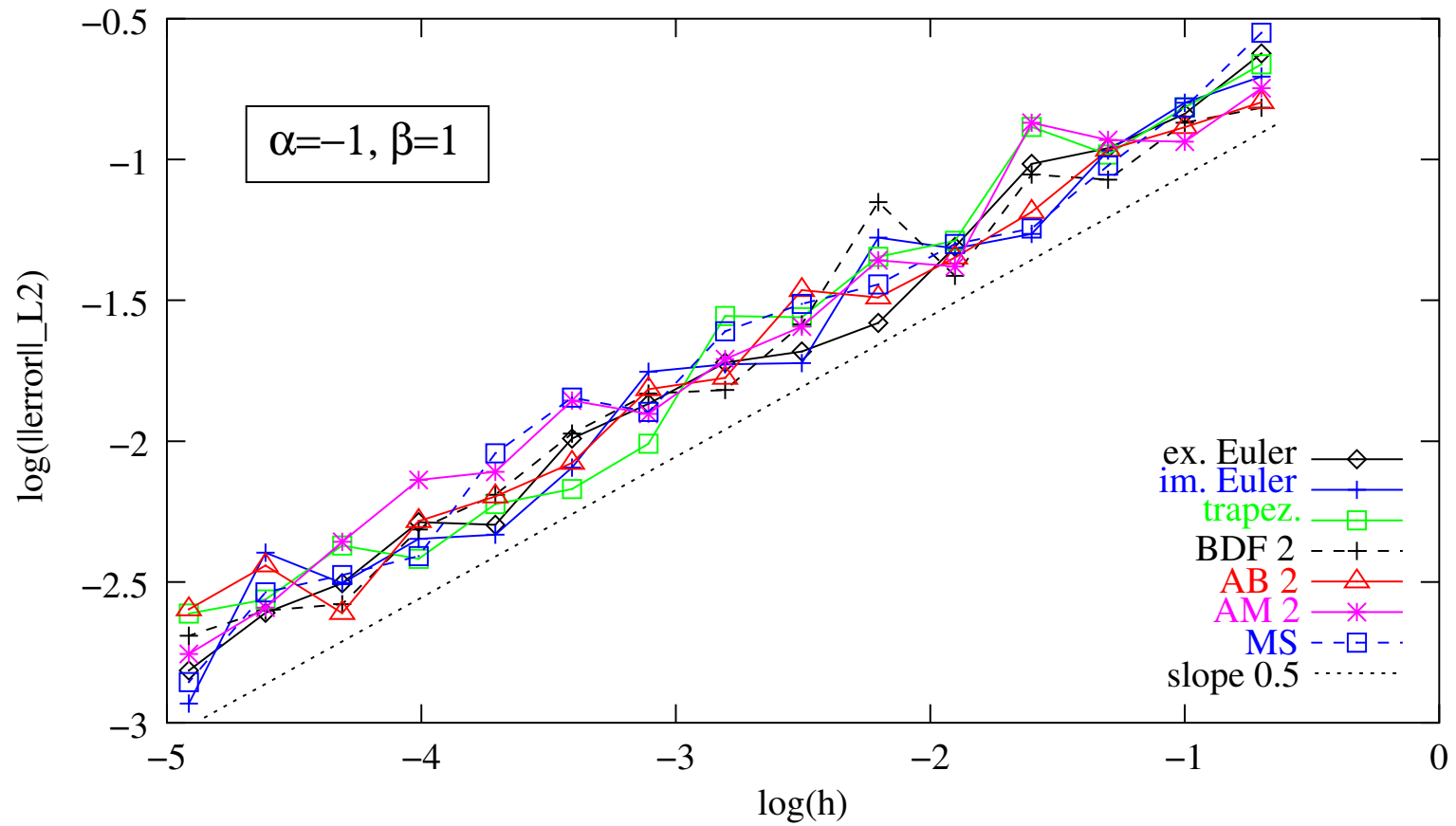


Figure 6

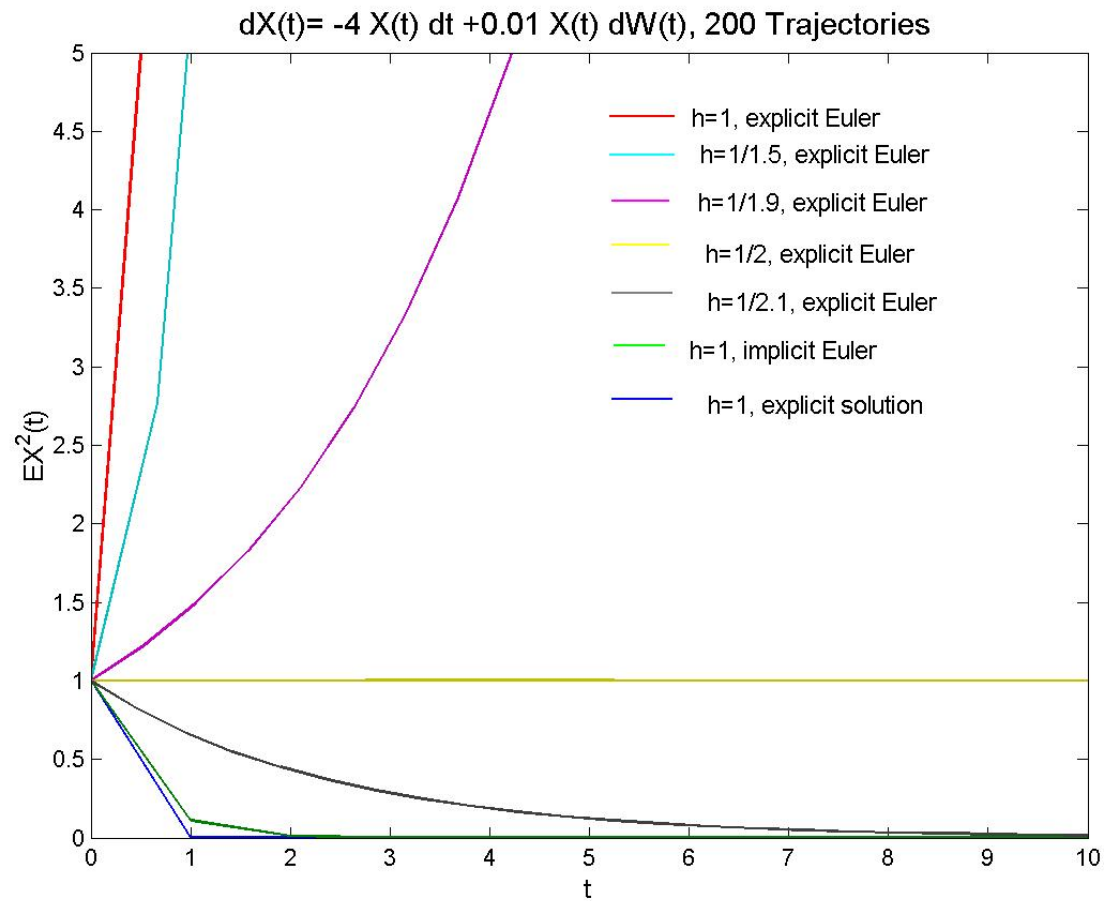
SRK-Maruyama

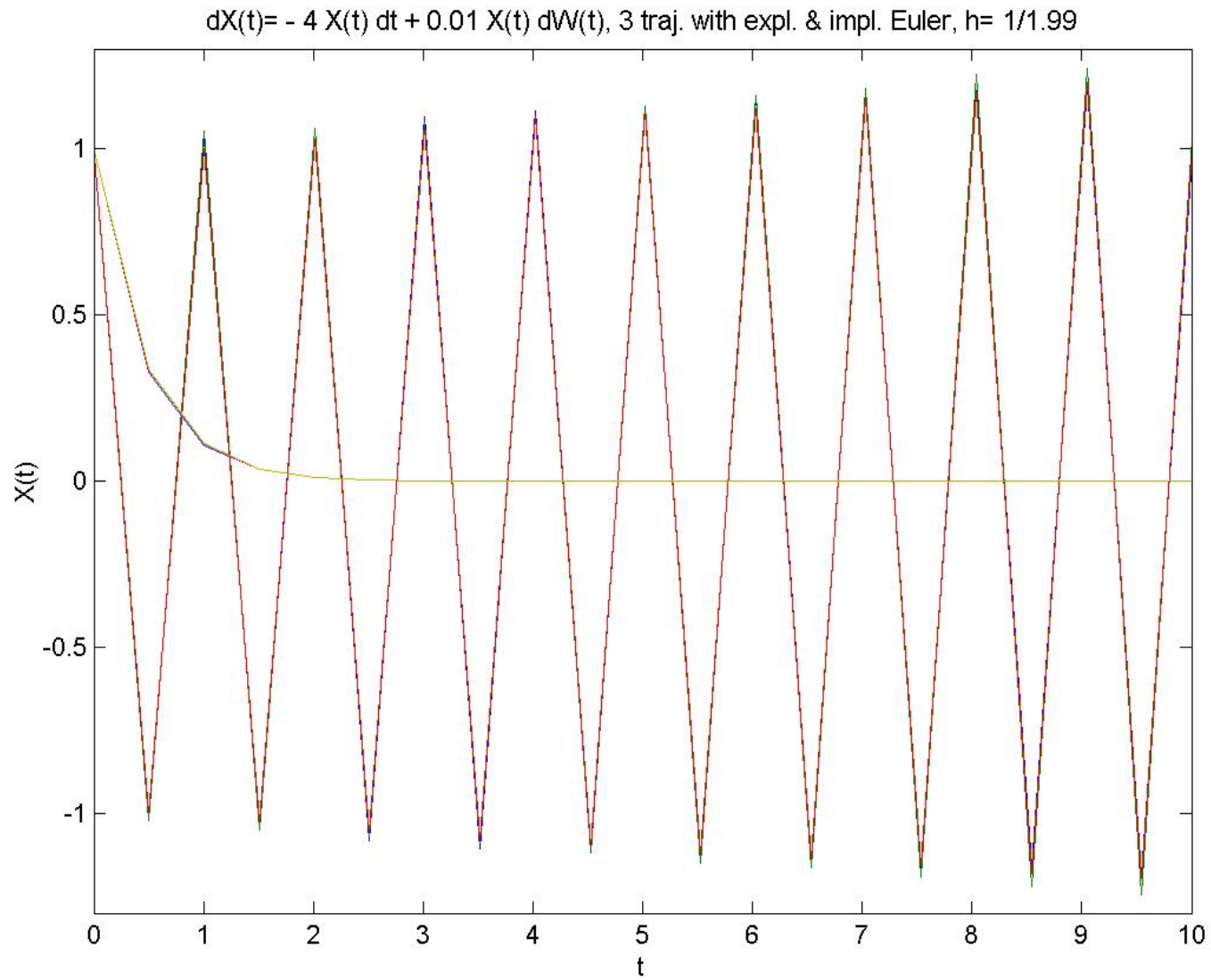
Grid on \mathcal{J} with constant step-size h and $t_n = n \cdot h$, $n = 0, 1, 2, \dots, N$.

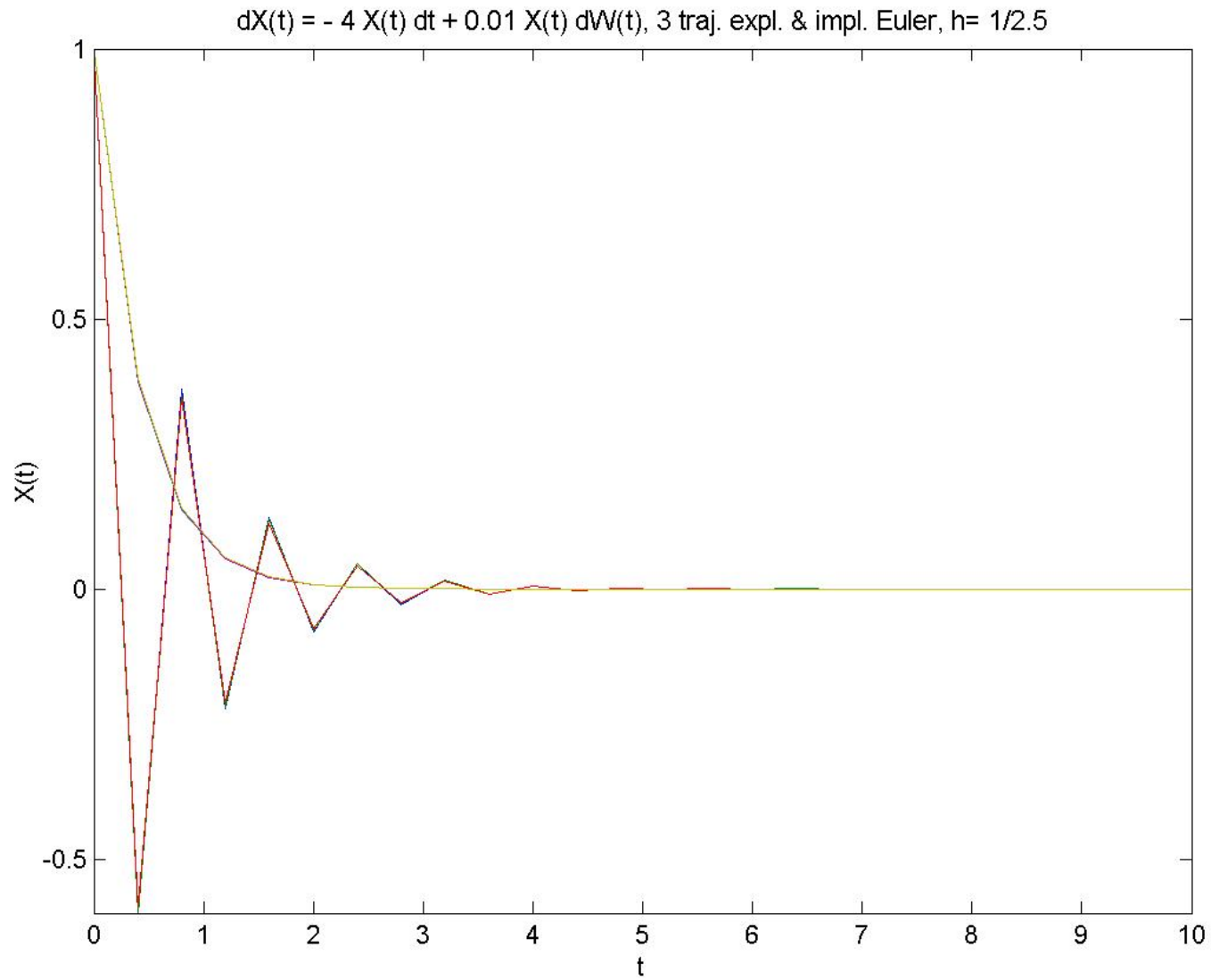
$$\begin{aligned} Y_0 &= X_0, \\ Y_{n+1} &= Y_n + \sum_{i=1}^s \beta_i f(t_n + c_i h, H_i) h + \sum_{r=1}^m g_r(t_n, Y_n) I_r^{t_n, t_n+h}, \\ H_i &= Y_n + \sum_{j=1}^s a_{ij} f(t_n + c_j h, H_j) h, \quad i = 1, \dots, s \end{aligned}$$

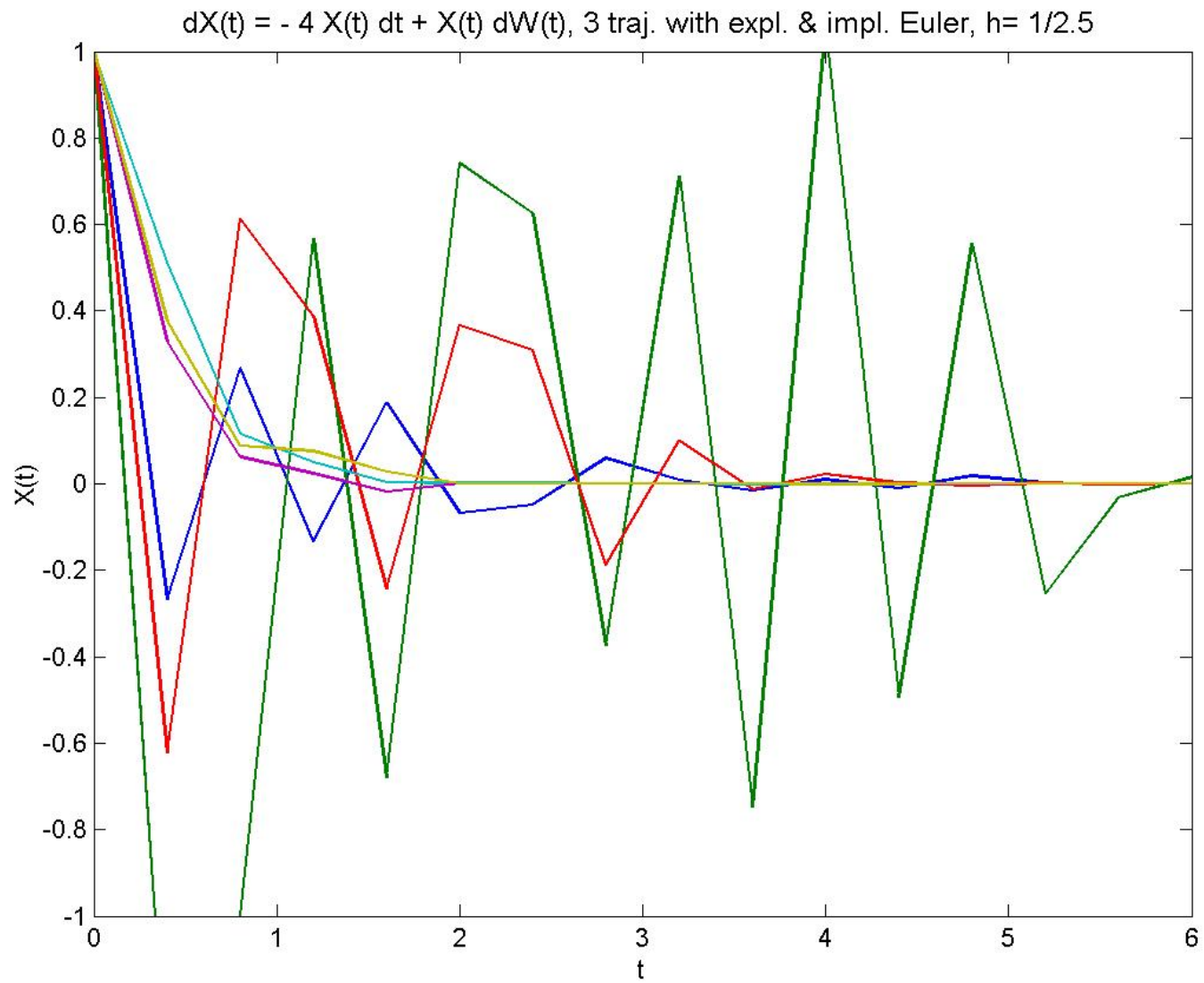
$$I_r^{t_n, t_{n+1}} = B_r(t_{n+1}) - B_r(t_n) \sim \mathcal{N}(0, h)$$

Stability behaviour









Asymptotic MS-stability of zero solutions

Def.: The **zero solution** of the SODE is termed

▶ *mean-square stable*, if for each $\epsilon > 0$, there exists a $\delta \geq 0$ such that the solution $X(t) = X(t; 0, X_0)$ exists for all $t \geq 0$ and $\mathbb{E}|X(t)|^2 < \epsilon$ whenever $t \geq 0$ and $\mathbb{E}|X_0|^2 < \delta$;

▶ *asymptotically mean-square stable*, if it is mean-square stable and if there exists a $\delta \geq 0$ such that whenever $\mathbb{E}|X_0|^2 < \delta$ we have

$$\mathbb{E}|X(t)|^2 \rightarrow 0 \quad \text{for } t \rightarrow \infty.$$

The definition for the zero solution of the numerical method is analogous.

Linear test equation, for $t \geq 0$, with $X(0) = X_0$, $\lambda, \mu, X_0 \in \mathbb{C}$,

$$dX(t) = \lambda X(t)dt + \mu X(t)dB(t), \quad (1)$$

with the complex geometric Brownian motion as exact solution.

Thm.: (e.g. in Arnold '74, Hasminskii '80)

The zero solution of (1) is asymptotically mean-square stable if

$$\operatorname{Re}(\lambda) < -\frac{1}{2} |\mu|^2$$

Linear stability analysis of Θ -method (D. Higham)

$$\begin{aligned} X_n &= X_{n-1} + h(\Theta f(t_n, X_n) + (1 - \Theta) f(t_{n-1}, X_{n-1})) \\ &\quad + \sum_{r=1}^m g_r(t_{n-1}, X_{n-1}) I_r^{t_{n-1}, t_n} \end{aligned}$$

applied to $dX(t) = \lambda X(t)dt + \mu X(t)dB(t)$ gives recurrence

$$X_{i+1} = (\tilde{a} + \tilde{b} \xi_i) X_i, \quad \text{where} \quad \tilde{a} = \frac{1 + (1-\theta)\lambda h}{1 - \theta\lambda h}, \quad \tilde{b} = \frac{\mu h^{\frac{1}{2}}}{1 - \theta\lambda h}.$$

Squaring and taking the expectation \Rightarrow **exact** one-step rec. for $\mathbb{E}|X_i|^2$

$$\mathbb{E}|X_{i+1}|^2 = (|\tilde{a}|^2 + 2|\tilde{a}||\tilde{b}|\mathbb{E}\xi_i + |\tilde{b}|^2\mathbb{E}\xi_i^2) \mathbb{E}|X_i|^2 = (|\tilde{a}|^2 + |\tilde{b}|^2) \mathbb{E}|X_i|^2$$

This recurrence will converge to zero, that is its zero solution will be asymptotically mean-square stable, iff $(|\tilde{a}|^2 + |\tilde{b}|^2) < 1$.

Weak Convergence

Weak approximations are concerned with calculating the expectation of some functional of the solution $\mathbb{E} \Psi(X(t_n))$ where Ψ could be the moments of the process or, of course the price function of an option! The measure is concerned with distributional properties of the processes, thus convergence measures the difference of $|\mathbb{E} \Psi(X(t_n)) - \mathbb{E} \Psi(X_n)|$,
key-word: [Monte-Carlo-methods](#).

(see Kloeden & Platen, Milstein & Tretyakov, Glasserman)

Euler and Milstein methods are the same methods!

Theorem(Milstein): if Ψ is sufficiently smooth and polynomially bounded and for sufficiently large r the $2r$ -th moments of the numerical approximation exist and are uniformly bounded wrt the number of time-steps, and, further, the one-step method under investigation satisfies

$$|\mathbb{E}(\Psi(X(t_n + h; t_n, x)) - \mathbb{E}\Psi(X_{n+1}(t_n, x)))| \leq K(x)h^{p+1}$$

where $X(t_n + h; t_n, x)$ denotes the solution of the SDE starting at time t with i.v. x , similarly for $X_{n+1}(t_n, x)$. Then

$$\max_{0 \leq n \leq N} |\mathbb{E} \Psi(X(t_n)) - \mathbb{E} \Psi(X_n)| \leq ch^p$$

where ψ needs to be $2(p + 1)$ times differentiable.

References

- [1] L. Arnold. *Stochastic Differential Equations: Theory and Applications*. Wiley-Interscience, New York, 1974.
- [2] E. Buckwar and R. Winkler, Multistep methods for SDEs and their application to problems with small noise, *SIAM J. Numer. Anal.* 44(2), pp. 779–803, 2006.
- [3] E. Buckwar, R. Horváth-Bokor and R. Winkler, Asymptotic mean-square stability of two-step methods for stochastic ordinary differential equations. *BIT* 46(2), pp. 261–282, 2006.
- [4] E. Buckwar, A. Rößler and R. Winkler, Stochastic Runge-Kutta methods for Itô-SODEs with small noise, submitted.

- [5] M. B. Giles, Variance reduction through multilevel Monte Carlo path calculations, in *Numerical methods for finance. Selected papers based on the presentations at the international conference on 'Numerical methods for finance' Dublin, Ireland, June 2006*, Eds.: J. A. D. Appleby et al., Chapman & Hall/CRC, Boca Raton, pp. 215–223, 2008.
- [6] M. B. Giles, Improved multilevel Monte Carlo convergence using the Milstein scheme, in *Monte Carlo and quasi-Monte Carlo methods 2006. Selected papers based on the presentations at the 7th international conference 'Monte Carlo and quasi-Monte Carlo methods in scientific computing', Ulm, Germany, August 2006*, Eds.: A. Keller et al., Springer, Berlin, pp. 343–358, 2008.
- [7] P. Glasserman, *Monte Carlo methods in financial engineering*, Springer, New York, 2004.

- [8] R. Z. Hasminskiĭ, *Stochastic Stability of Differential Equations*, Sijthoff and Noordhoff, 1981.
- [9] D. J. Higham. Mean-square and asymptotic stability of the stochastic theta method. *SIAM J. Numer. Anal.*, 38(3), pp. 753–769, 2000.
- [10] P. E. Kloeden and E. Platen, *Numerical Solution of Stochastic Differential Equations*, Springer, Berlin, 1992.
- [11] G. N. Milstein and M. V. Tretyakov, *Stochastic Numerics for Mathematical Physics*, Springer–Verlag, Berlin, 2004.
- [12] R. Winkler, Stochastic differential algebraic equations of index 1 and applications in circuit simulation, *J. Comput. Appl. Math.* 163(2), pp. 435–463, 2004.